

This is a demonstration of the CoSAR-TS project funded by the Agents/DAML program of the US Defense Advanced Research projects Agency (DARPA) and which involved joint research between the Artificial Intelligence Applications Institute (AIAI) in the School of Informatics at the University of Edinburgh and the Florida Institute for Human & Machine Cognition (IHMC) at the University of West Florida

The objective was to study and develop a demonstrator for Task Support in a realistic and highly dynamic Coalition Search and Rescue scenario. Research at AIAI on I-X Task Support and intelligent agent systems was linked with IHMC work on KAoS Agent Domain and Policy Management concepts. OWL representations, and OWL-S descriptions of agents and services were utilized.

More details of the systems involved papers describing the work, and other resources can be found on the [CoSAR-TS Web Site](#).

<http://www.aiai.ed.ac.uk/project/cosar-ts/>

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Further Information

Coalition Search and Rescue Task Support Project Web Site <http://www.aiai.ed.ac.uk/project/cosar-ts/>

I-X Web Site <http://www.aiai.ed.ac.uk/project/ix/>

Note that the binni.org URL mentioned at the end of the video is no longer active. The same information is on the [KSCO](#)

Binni Web Site <http://ksco.info/binni/>

Artificial Intelligence Applications Institute <http://www.aiai.ed.ac.uk/>

Florida Institute for Human & Machine Cognition <http://ihmc.us/>

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This is a demonstration of the I-Globe project which involved joint research between the Artificial Intelligence Applications Institute (AIAI) in the School of Informatics at the University of Edinburgh and the Agents Technology Group (ATG) in the Department of Cybernetics within the Faculty of Electrical Engineering at the Czech Technical University in Prague.

More details of the systems involved papers describing the work, and video links can be found on the [I-Globe Web Site](http://www.aiai.ed.ac.uk/project/i-globe/). <http://www.aiai.ed.ac.uk/project/i-globe/>

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